

Below are links to related papers, books and dissertations where you can read more of the details for things that are of interest to you. We've included LinkedIn links in each project so you can get a better idea of the career progressions of our students, something that we're very proud of.

- Machine learning for cognitive radio and 5G wireless. (Margaret Rooney)
 - M. M. Rooney and M. K. Hinders, "Machine Learning for Medium Access Control Protocol Recognition in Communications Networks," in IEEE Access, vol. 9, pp. 110762-110771, 2021, doi: 10.1109/ACCESS.2021.3102859.
 - Margaret Rooney, Working title: Machine learning, signal identification and signal classification to infer network processes, William and Mary, Department of Applied Science Doctoral Dissertation, expected completion: 2021.
- Lamb wave detection of oil under Arctic ice floes. (Elizabeth S. Simons, Spencer Kirn)
 - Geo-Referencing Identification (GRID) system for the tagging and tracking of assets from storage through deployment for emergency response, (with B. Schreib et al.) final technical report for DOI/BSEE #E14PC00027, 2015.
 - Tagging of Oil under Ice for Future Recovery (with B. Schreib et al.) final technical report for DOI/BSEE #E14PC00028, 2016.
 - Equip GRID and GRIDSAT Tags with Accelerometers to Measure Ocean Waves (with B. Schreib et al.) final technical report for DOI/BSEE #E16PC00015, 2017.
 - Tagging of Oil Under Ice Phase II: Ice Floe Tracking System, (with B. Schreib et al.) final technical report for DOI/BSEE #E17PC00022, 2019. Spencer L. Kirn and Mark Hinders, Design Simulations Report, 82 pages, February 9, 2018.
 - Development of Underwater Beacon for Arctic Through-Ice Communication via Satellite (with E.D. Skinner, S.L. Kirn) Cold Regions Science and Technology, Vol. 160C, pp. 58-79 (2019). https://doi.org/10.1016/j.coldregions.2019.01.010
- Smart container tracking with infrared catadioptric imaging. (Victor Trujillo II)
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 - Wen Gao, Air Coupled Ultrasound Imaging for Robot Situational Awareness, William and Mary, Department of Applied Science Doctoral Dissertation, April 2005. Mobile Robot Sonar Interpretation Algorithm for Distinguishing Trees from Poles (with Wen Gou) Robotics and Autonomous Systems, Vol. 53, 89-98 (2005).
 - Mobile Robot Sonar Deformable Template Algorithm for Distinguishing Fences, Hedges and Low Walls (with Wen Gou) in "Reviews of Progress in Quantitative Nondestructive Evaluation Vol. 25", D.O. Thompson and D.E. Chimenti, eds. pp. 1523-1530 (2006).
 - Sonar Backscatter Interpretation for Outdoor Mobile Robot Navigation, (with W. Gao and W. Fehlman) invited chapter in "Mobile Robots, Perception & Navigation" pp. 69-90, Sascha Kolski, ed. Advanced Robotic Systems, Vienna, Austria, pro Literatur Verlag (2007).
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